

Autostereoscopic transparent display using a wedge light guide and a holographic optical element

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Abstract: We present a novel transparent autostereoscopic display consisting of laser picoprojectors, a wedge light guide and a holographic optical element. Such a display can superimpose 3D data on the real world without any wearables. © 2019 The Author(s)

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1. Motivation

Augmented Reality (AR) dedicated systems such as Hololens and Meta provide stereoscopic augmentation using transparent displays but require to wear a headset. We propose a transparent display similar to a head-up display that provides autostereoscopic capabilities: separate views are addressed to each eye independently and without wearing any glasses or headset. The user can also move the head horizontally and perceive motion parallax without tracking. Our work is inspired from a non-transparent multi-projection display using conventional optics in combination with a wedge light guide [1]. On the contrary, our work results in a transparent display.

2. Method

The principle of our display is to couple beams from multiple "laser beam-steering" picoprojectors into a transparent light guide and then to redirect each beam to separate viewing zones (VZ) using a transparent Holographic Optical Element (HOE).

The light guide we use is a wedge-shaped light guide [2]: rays are guided with total internal reflection in a slab (referred to as the "expansion part" in Figure 2). At the "wedge part", one face of the guide is tilted relatively to the other so that the rays' angles with respect to the normal decrease at each bounce, until they reach the critical angle and escape the guide. This shape is extruded so that the projected image can expand in one dimension while being guided in the other. Rays leave the guide collimated with an angle nearly parallel to the guide direction, while they still fan out on the other direction (perpendicularly to the figure).

A transmission HOE is clamped to the wedge exit surface in order to redirect light rays from projectors to pre-defined VZs as shown in Figure 2(a). Figure 2 also shows that we only use a small portion of the wedge area that corresponds to the lateral expansion of the projected images. The HOE achieves multiple optical functions: a Fresnel mirror that straightens each ray leaving the guide at grazing angle to a normal direction, a cylindrical lens that turns the diverging beam into a converging beam, and an anisotropic diffuser that makes each point of the VZs lit by every point of the hologram.

We have recorded the transfer function of the central position of the projector: the signal beam reproduces the conjugated beam of the output of the wedge guide, incident at grazing angle on the hologram, while the object beam is created by lighting a 3x10cm diffuser (size of the VZ) located at 50cm (observation distance) from the hologram. The lateral size of 3cm of each VZ is chosen according to the mean interpupillary distance.

The beams from adjacent projectors are reconstructed within the angular Bragg limit of the HOE: an angle shift of $\Delta\theta$ in the input from the angle of recording results in the same shift on the output while $\Delta\theta < \Delta\theta_{Bragg}$. In this

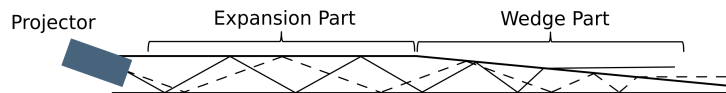


Fig. 1. Principle of a wedge guide

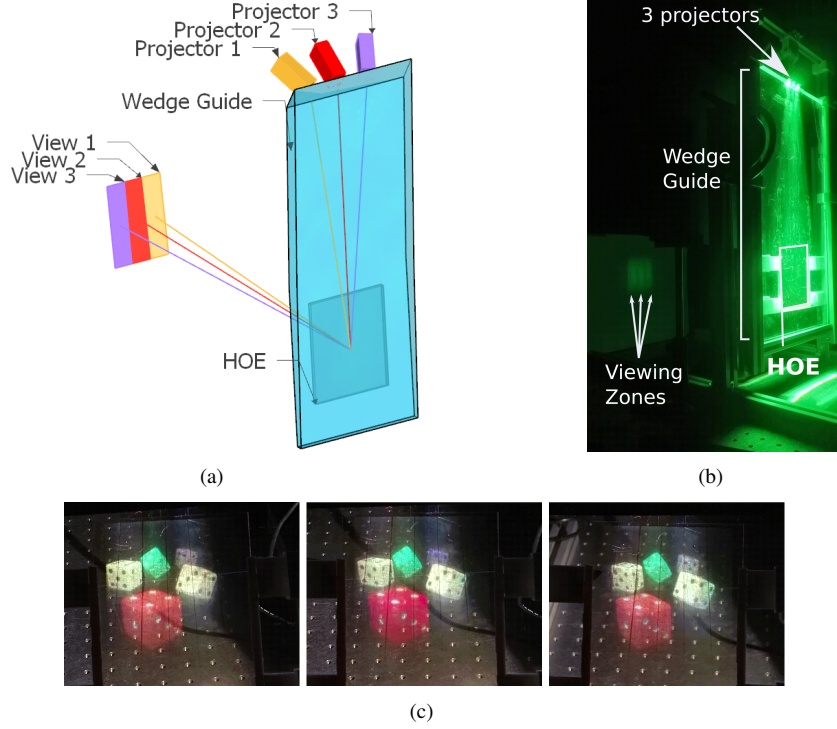


Fig. 2. (a) Drawing of light paths from three projectors to the corresponding VZs (b) Picture of the current prototype demonstrating the hologram function (c) Pictures taken from three different VZs

way, the VZs can be displayed side by side along the field of view if the projectors are properly positioned at the entrance of the wedge guide. In normal conditions of observation and lighting ($\Delta\theta \gg \Delta\theta_{\text{Bragg}}$), only the light from the projectors is diffracted, and the HOE is perceived as transparent. We have measured $\Delta\theta_{\text{Bragg}} \approx \pm 10^\circ$ for our HOE, imposing a maximum number of 9 projectors in our current setup.

We have recorded a monochromatic green HOE and a RGB multiplexed HOE. The monochromatic one behaves as expected, whereas the full-color one presents some chromatic aberrations that are due to a too large wavelength selectivity of each grating.

In order to create and display content on our device, we use a custom software written in C++/OpenGL that renders multiview images after a calibration step. The calibration consists in correcting the guide distortion and aligning images from different projectors.

3. Conclusion

We have demonstrated the feasibility of a compact, autostereoscopic transparent display with multiple projectors and a custom HOE. Our current prototype has three views but we think it is theoretically able to generate up to 9 views, providing binocular vision and horizontal motion parallax. Vertical parallax could be implemented with head tracking, for example. The views are located 50cm in front of the display, they are 3cm wide and 10cm high. These values are fixed once the HOE is recorded; they result from our choices and can be changed in the recording step. This display has great potential for AR applications such as augmented exhibitions in museums or shops, head-up displays for vehicles or aeronautics, and industrial maintenance, among others.

4. Acknowledgments

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